3-phase motor driver
BA6840BFS / BA6840BFP-Y / BA6840BFP / BA6842BFS

The BA6840BFS, BA6840BFP-Y, BA6840BFP, and BA6842BFS are one-chip ICs designed for driving CD-ROM motors.
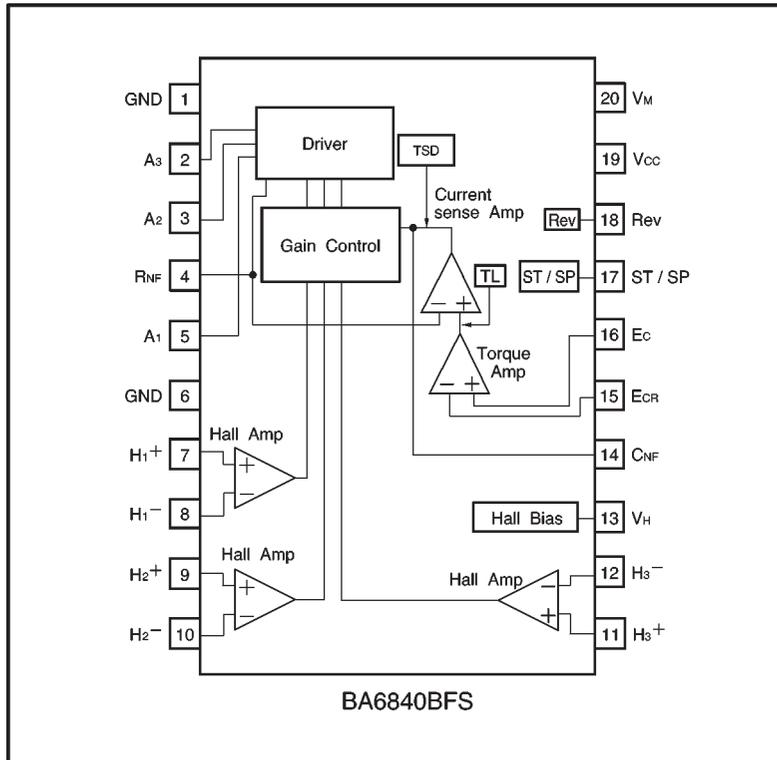They are high performance-ICs with a 3-phase, full-wave, pseudo-linear drive system.

●Applications
CD-ROM / RW, DVD-ROM / PLAYER

●Features
1) 3-phase, full-wave, pseudo-linear drive system.
2) Start / stop pin; power saving during stop mode.
3) Internal current limit circuit.
4) Internal thermal shutdown circuit.
5) Internal hall bias circuit.

●Block diagram

BA6840BFS

●Absolute maximum ratings (Ta = 25°C)

Parameter		Symbol	Limits	Unit
Power supply voltage		V_{CC}	7	V
		V_M	16	
Power dissipation	BA6840BFS	Pd	930*1	mW
	BA6840BFP-Y		1450*2	
	BA6840BFP		1700*3	
	BA6842BFS		1000*4	
Operating temperature		Topr	−20~+75	℃
Storage temperature		Tstg	−55~+150	℃
Output current		I_{OUT}	1300	mA

∗1 Reduced by 7.5 mW for each increase in Ta of 1℃ over 25℃.
∗2 Reduced by 11.6 mW for each increase in Ta of 1℃ over 25℃.
∗3 Reduced by 13.6 mW for each increase in Ta of 1℃ over 25℃.
∗4 Reduced by 8.0 mW for each increase in Ta of 1℃ over 25℃.
∗1~4 When mounted on a 90×50×1.6 mm glass epoxy board.
　　　Should not exceed Pd or ASO values.

●Recommended operating conditions

Parameter	Symbol	Min.	Typ.	Max.	Unit
Operating power supply voltage	V_{CC}	4.25	—	5.50	V
	V_M	3.0	—	15	V

ROHM

●Electrical characteristics (unless otherwise noted, Ta = 25°C, V$_{CC}$ = 5V, V$_M$ = 12V)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
〈Overall〉						
Supply current 1	I$_{CC}$1	—		0.2	mA	Start / stop OFF
Supply current 2	I$_{CC}$2	—	3.6	6.0	mA	Start / stop ON inputs : H, M and L
〈Start / stop〉						
ON voltage	V$_{PSON}$	3.5	—	—	V	
OFF voltage	V$_{PSOFF}$	—	—	1.5	V	
〈Hall bias〉						
Hall bias voltage	V$_{HB}$	—	0.9	1.5	V	I$_{HB}$＝10mA
〈Hall amplifier〉						
Input bias current	I$_{HA}$	—	0.25	1.0	μA	
Common-mode input voltage	V$_{HAR}$	1.5	—	4.0	V	
Minimum input level	V$_{INH}$	50	—	—	mV$_{P-P}$	
〈Torque control〉						
Input voltage	E$_C$	1.0	—	4.0	V	
Offset voltage ＋	E$_{cofs}$＋	20	50	80	mV	For E$_{CR}$= 2.5 V
Offset voltage －	E$_{cofs}$－	－80	－50	－20	mV	
Input current	E$_{CIN}$	—	0.5	2.0	μA	E$_C$＝E$_{CR}$＝2.5V
Input/output gain	G$_{EC}$	0.41	0.51	0.61	A/V	R$_{NF}$＝0.5Ω, when measured at E$_C$＝2points: 1.5V and 2.0V E$_C$＝2points: 3.0V and 3.5V
〈Output〉						
Output saturation high level voltage	V$_{OH}$	—	1.0	1.6	V	I$_O$＝－600mA
Output saturation low level voltage	V$_{OL}$	—	0.4	0.9	V	I$_O$＝600mA
Torque limit current	I$_{TL}$	560	700	840	mA	R$_{NF}$＝0.5Ω

◎Not designed for radiation resistance

●Electrical characteristic curves
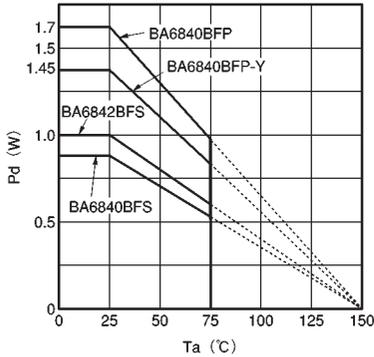

Fig.1   Power dissipation curves

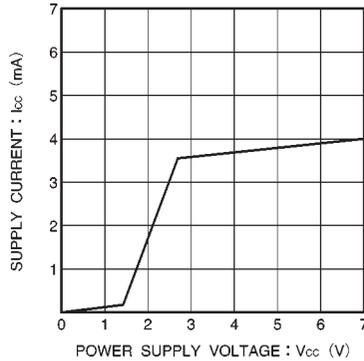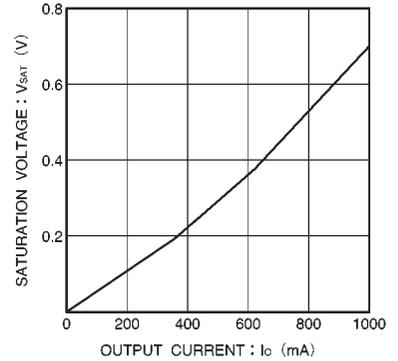
Fig.2   Supply current vs.
         power supply voltage

Fig.3   Low-level output
         saturation voltage vs.
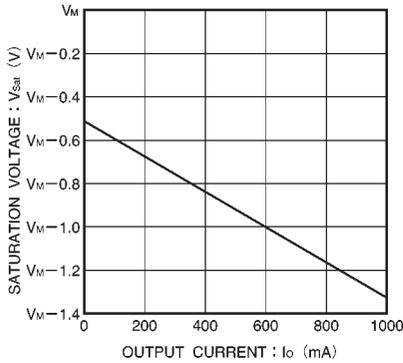   output current

Fig.4   High-level output
         saturation voltage vs.
         output current

ROHM

●Circuit operation

(1)　Hall input ～ output

The 3-phase Hall signal is amplified in the hall amplifiers and sent to the matrix section, where the signal is further amplified and combined. After the signal is converted to a current in the amplitude control circuit, the current is supplied to the output driver, which then provides a motor drive current. The phases of the Hall input signal, output voltage, and output current are shown in Fig. 5.
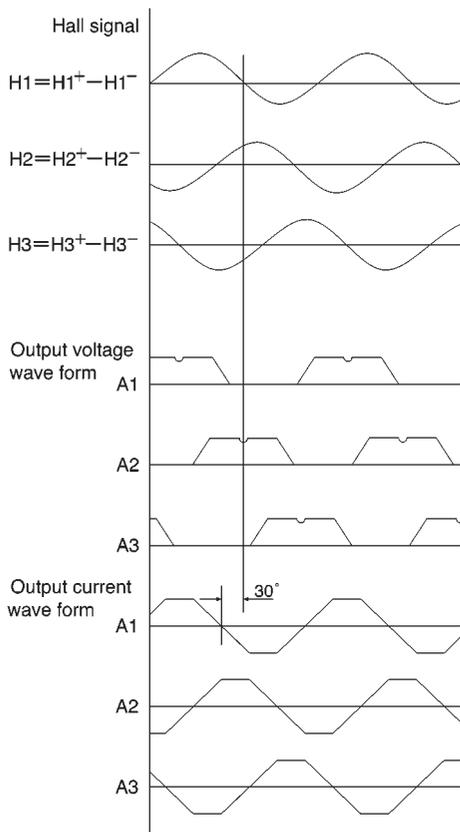
Hall signal

$H1 = H1^+ - H1^-$

$H2 = H2^+ - H2^-$

$H3 = H3^+ - H3^-$

Output voltage
wave form　A1

A2

A3

Output current
wave form　A1

A2

A3

Fig. 5

(2)　Torque control pin

The R_{NF}-pin current depends on the torque control input voltage (EC) as shown in Fig. 6.

Fig. 6

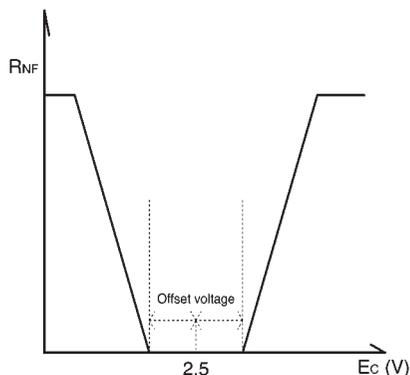|	Reverse pin voltage	
	H	L
$E_{CR} < E_C$	Reverse	Forward
$E_{CR} > E_C$	Stop	Reverse

(3)　Start / stop pin

The motor is in the run mode when the pin input voltage is 3.5V or more, and in the idle mode (all output transistors are off) when the voltage is 1.5V or less.

(4)　Power ground pin (R_{NF} pin)

The R_{NF} pin is the output stage ground pin. Connect a resistor (0.5Ω recommended) between this pin and the ground to monitor the output current.

(5)　Phase compensation pin (C_{NF} pin)

Connect and adjust a capacitor between this pin and the ground if the output tends to oscillate.

●Pin descriptions

Pin name	BA6840BFS	BA6840BFP-Y	BA6840BFP	BA6842BFS	Function
GND	1	FIN	FIN	8, 9, 23, 24, 25	Ground
A_3	2	3	3	1	Output
A_2	3	4	4	4	Output
R_{NF}	4	6	5	5	Current detector ouput
A_1	5	7	6	7	Output
GND	6	8	7	10	Ground
$H_1{}^+$	7	9	9	11	Hall signal input
$H_1{}^-$	8	10	10	12	Hall signal input
$H_2{}^+$	9	11	13	13	Hall signal input
$H_2{}^-$	10	12	14	15	Hall signal input
$H_3{}^+$	11	13	15	16	Hall signal input
$H_3{}^-$	12	14	16	17	Hall signal input
V_H	13	15	17	18	Hall bias
C_{NF}	14	17	20	21	Capacitor for phase compensation connection
E_{CR}	15	18	21	22	Standard output current control
E_C	16	19	22	26	Output current control
ST / SP	17	20	23	27	Start / stop switch
REV	18	22	24	29	Reverse
V_{CC}	19	23	25	30	Power supply
V_M	20	24	26	31	Motor power supply

●Input / output circuits

(1)   Start / stop

(2)   Reversing pin
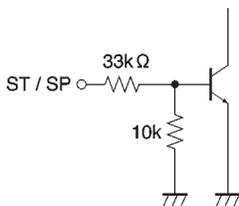
(3)   Hall bias

(Resistances are typical values.)

Fig. 7
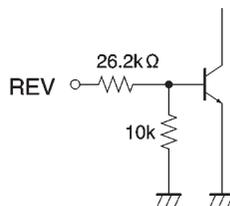
(Resistances are typical values.)

Fig. 8
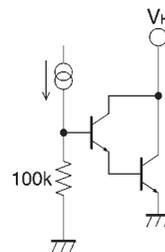
(Resistances are typical values.)

Fig. 9

ROHM

(4) Torque control input

E$_{CR}$
1k

1k
E$_C$
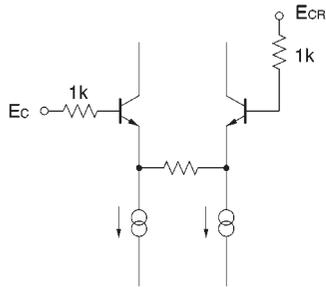
(Resistances are typical values.)

Fig. 10

(5) Coil output

V$_M$

A1   A2   A3

R$_{NF}$
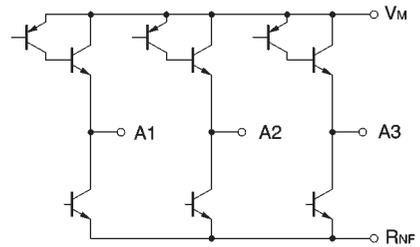
Fig. 11

(6) Hall input (H1$^+$, H1$^-$, H2$^+$, H2$^-$, H3$^+$, H3$^-$)

1kΩ

1kΩ
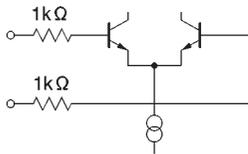
(Resistances are typical values.)

Fig. 12

●Operation notes

(1) Start / stop

The I / O equivalent circuit of the start / stop pin is shown in Fig. 7. The pin has a temperature dependence of $-7mV / °C$, and the resistance can vary ±30%. Take the temperature effect into consideration when designing your application.

(2) Hall input

The Hall input equivalent circuit is shown in Fig. 12. The Hall devices can be connected in either series or parallel.

(3) Thermal shutdown circuit (TSD)

The circuit puts the coil outputs (A$_1$, A$_2$, and A$_3$) to the open state at the temperature of 175°C (typical). There is a temperature difference of about 15°C between the temperatures at which the circuit is activated and deactivated.
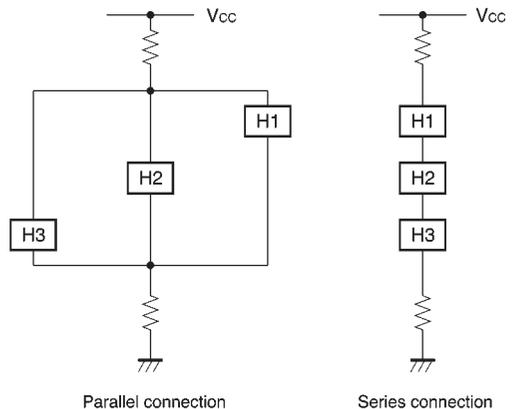
V$_{CC}$ V$_{CC}$

H1   H1

H2   H2
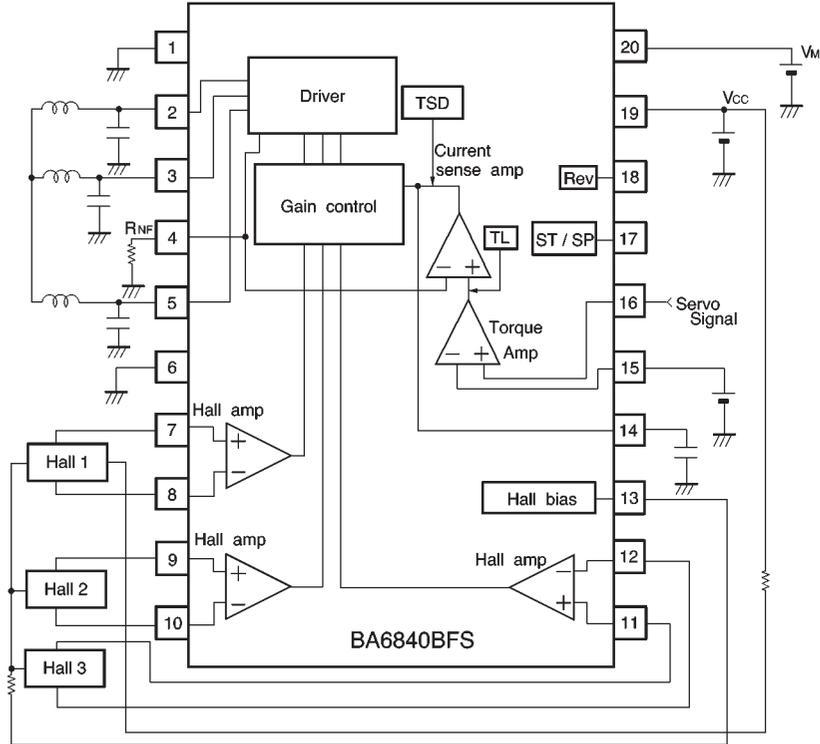
H3   H3

Parallel connection   Series connection

Fig. 13

●Application example

Fig.14

●External dimensions (Units: mm)

BA6840BFS

SSOP-A20

BA6840BFP-Y

HSOP25

BA6840BFP

HSOP28

BA6842BFS

SSOP-P32