

**312 OUTPUT TFT-LCD SOURCE DRIVER
(COMPATIBLE WITH 64 GRAY SCALES)**

The μ PD16633 is a source driver for TFT-LCDs capable of dealing with displays with 64 gray scales. Data input is based on digital input configured as 6 bits by 6 dots (2 pixels), which can realize a full-color display of 260,000 colors by output of 64 values γ -corrected by an internal D/A converter and 5-by-2 external power modules. Because the output dynamic range is as large as 9.8 V_{P-P}, level inversion operation of the LCD's common electrode is rendered unnecessary. Also, to be able to deal with dot-line inversion when mounted on a single side, this source driver is equipped with a built-in 6-bit D/A converter circuit whose odd output pins and even output pins respectively output gray scale voltages of differing polarity. Assuring a maximum clock frequency of 45 MHz when driving at 3.0 V, this driver is applicable to XGA-standard TFT-LCD panels.

FEATURES

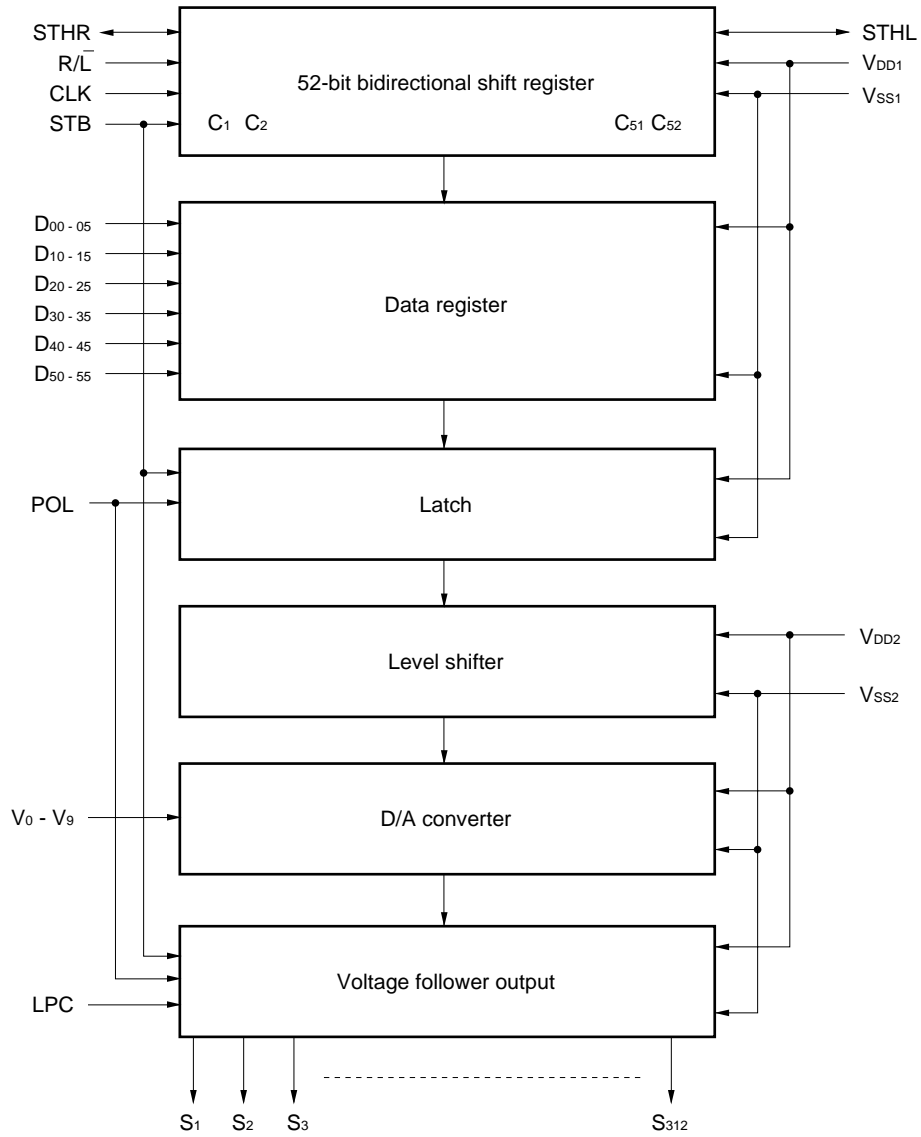
- Capable of outputting 64 values by means of 5-by-2 external power modules (10 units) and a D/A converter
- Output dynamic range 9.8 V_{P-P} min. (@V_{DD2} = 10.0 V)
- CMOS level input
- Input of 6 bits (gradation data) by 6 dots
- High-speed data transfer: $f_{max.} = 45$ MHz (internal data transfer speed when operating at 3.0 V)
- 312 outputs
- Single bank arrangement is possible (loaded with slim TCP)

ORDERING INFORMATION

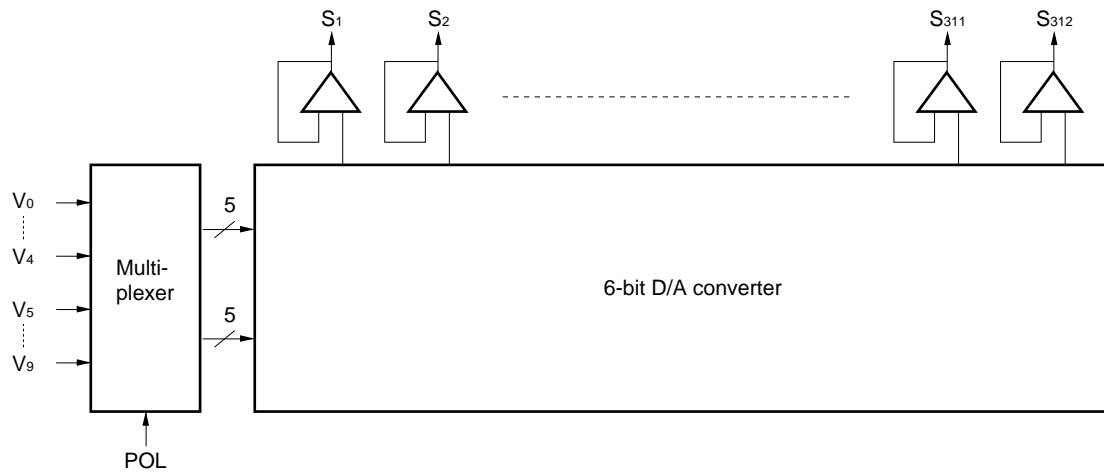
Part Number	Package
μ PD16633N-xxx	TCP (TAB package)

The TCP's external shape is customized. To order your TCP's external shape, please contact a NEC salesperson.

1. BLOCK DIAGRAM



2. RELATIONSHIP BETWEEN OUTPUT CIRCUIT AND D/A CONVERTER



POL	S_{2n-1}	S_{2n}
L	V_0 to V_4	V_5 to V_9
H	V_5 to V_9	V_0 to V_4

S_{2n-1} (odd output), S_{2n} (even output) $n = 1, 2, \dots, 156$

3. PIN FUNCTIONS

Pin Symbol	Pin Name	Description
S ₁ to S ₃₁₂	Driver output	The D/A converted 64-gray-scale analog voltage is output.
D ₀₁ to D ₀₅	Display data input	The display data is input with a width of 36 bits, viz., the gray scale data (6 bits) by 6 dots (2 pixels). D _{X0} : LSB, D _{X5} : MSB
D ₁₀ to D ₁₅		
D ₂₀ to D ₂₅		
D ₃₁ to D ₃₅		
D ₄₀ to D ₄₅		
D ₅₀ to D ₅₅		
R/L	Shift direction switching input	These refer to the start pulse input/output pins when cascades are connected. The shift directions of the shift registers are as follows. R/L = H: STHR input, S ₁ → S ₃₁₂ , STHL output R/L = L: STHL input, S ₃₁₂ → S ₁ , STHR output
STHR	Right shift start pulse input/output	R/L = H: Becomes the start pulse input pin. R/L = L: Becomes the start pulse output pin.
STHL	Left shift start pulse input/output	R/L = H: Becomes the start pulse output pin. R/L = L: Becomes the start pulse input pin.
CLK	Shift clock input	Refers to the shift register's shift clock input. The display data is incorporated into the data register at the rising edge. At the rising edge of the 52th clock after the start pulse input, the start pulse output reaches the high level, thus becoming the start pulse of the next-stage driver. The initial-stage driver's 52th clock becomes valid as the next-stage driver's start pulse is input. If 54 clock pulses are input after input of the start pulse, input of display data is halted automatically. The contents of the shift register are cleared at the STB's rising edge.
STB	Latch input	The contents of the data register are transferred to the latch at the rising edge. And, at the falling edge, the gray scale voltage is supplied to the driver. It is necessary to ensure input of one pulse per horizontal period.
LPC	Low power control input	The output buffer constant current source is blocked, reducing current consumption. In lower power mode (LPC = 'H': DC-level input possible), the ordinary static current consumption can be reduced by approx. 50%. The condition that low power mode can be used is that the load constant is at least 10 kΩ + 50 pF.
V ₀ to V ₉	γ -corrected power supplies	Input the γ -corrected power supplies from outside. Make sure to maintain the following relationships. During the gray scale voltage output, be sure to keep the gray scale level power supply at a constant level. V _{DD2} > V ₀ > V ₁ > V ₂ > V ₃ > V ₄ > V ₅ > V ₆ > V ₇ > V ₈ > V ₉ > V _{SS2}
TEST	Test pin	Set it to 'OPEN'.
V _{DD1}	Logic power supply	3.3 V ± 0.3 V
V _{DD2}	Driver power supply	10 to 13.5 V
V _{SS1}	Logic ground	Grounding
V _{SS2}	Driver ground	Grounding

- Cautions 1.** The power start sequence must be V_{DD1}, logic input, and V_{DD2} & V₀ to V₉ in that order. Reverse this sequence to shut down. (Simultaneous power application to V_{DD2} and V₀ to V₉ is possible.)
- 2.** To stabilize the supply voltage, please be sure to insert a 0.1 μ F bypass capacitor between V_{DD1}-V_{SS1} and V_{DD2}-V_{SS2}. Furthermore, for increased precision of the D/A converter, insertion of a bypass capacitor of about 0.01 μ F is also advised between the γ -corrected power supply terminals (V₀, V₁, V₂, ..., V₉) and V_{SS2}.

4. RELATIONSHIP BETWEEN INPUT DATA AND OUTPUT VOLTAGE VALUE

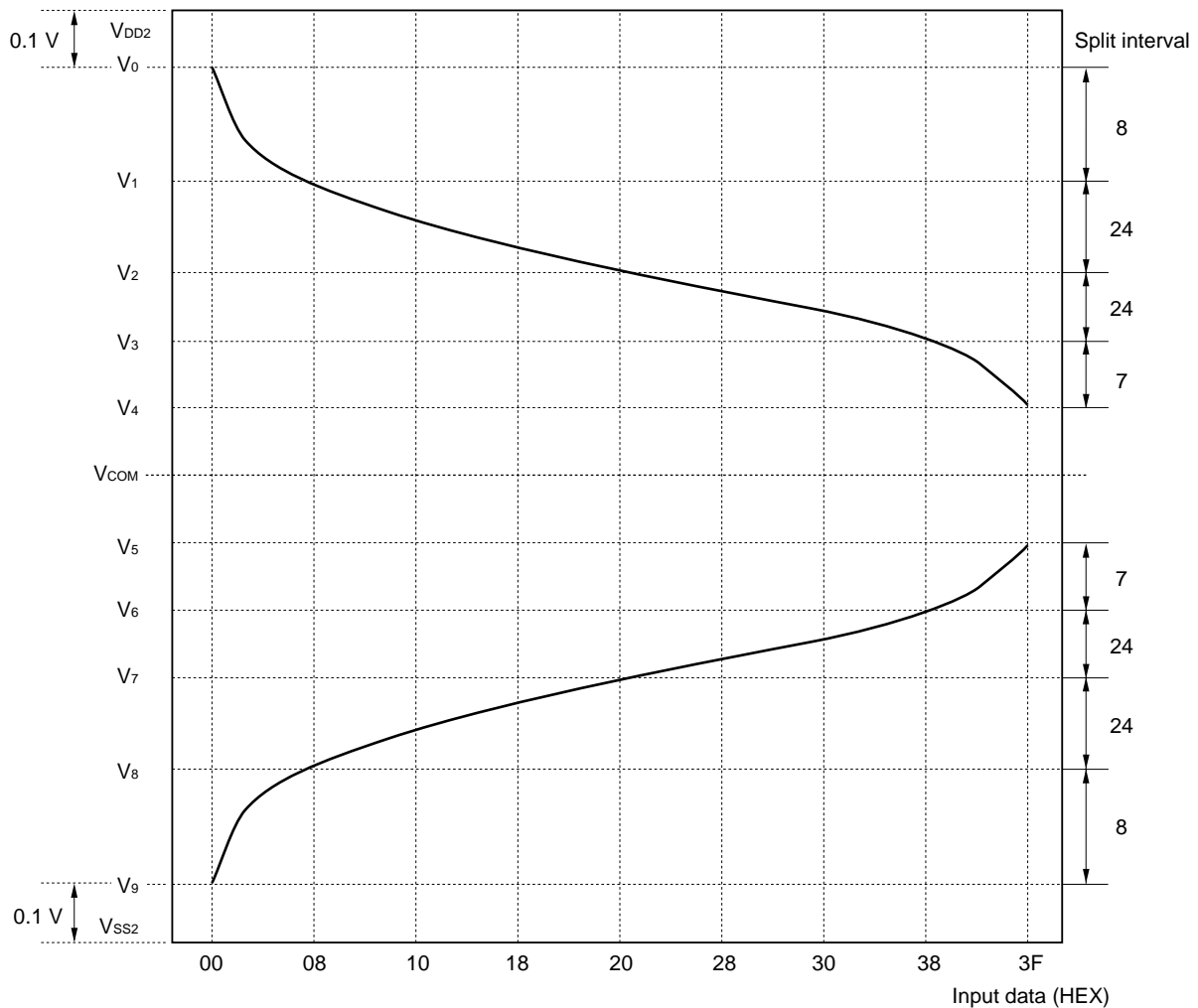
This product incorporates a 6-bit D/A converter whose odd output pins and even output pins output respectively gray scale voltages of differing polarity with respect to the LCD's counter electrode (common electrode) voltage. The D/A converter consists of ladder resistors and switches. The ladder resistors r_0 to r_{62} are so designed that the ratios between the LCD panel's γ -corrected voltages and V_0' to V_{63}' and V_0'' to V_{63}'' are roughly equal; and their respective resistance values are as shown on page 9. Among the 5-by-2 γ -corrected voltages, input gray scale voltages of the same polarity with respect to the common voltage, for the respective five γ -corrected voltages of V_0 to V_4 and V_5 to V_9 . If fine gray scale voltage precision is not necessary, the voltage follower circuit supplied to the γ -corrected power supplies V_1 to V_3 and V_6 to V_8 can be deleted.

Figure 1 shows the relationship between the driving voltages such as liquid-crystal driving voltages V_{DD2} and V_{SS2} , common electrode potential V_{COM} , and γ -corrected voltages V_0 to V_9 and the input data. Be sure to maintain the voltage relationships of $V_{DD2} > V_0 > V_1 > V_2 > V_3 > V_4 > V_5 > V_6 > V_7 > V_8 > V_9 > V_{SS2}$. Figures 2-1 and 2-2 show the relationship between the input data and the output data. Table 1 shows the resistance values of the resistor strings.

This driver IC is designed for single-sided mounting. Therefore, please do not use it for γ -corrected power supply level inversion in double-sided mounting.

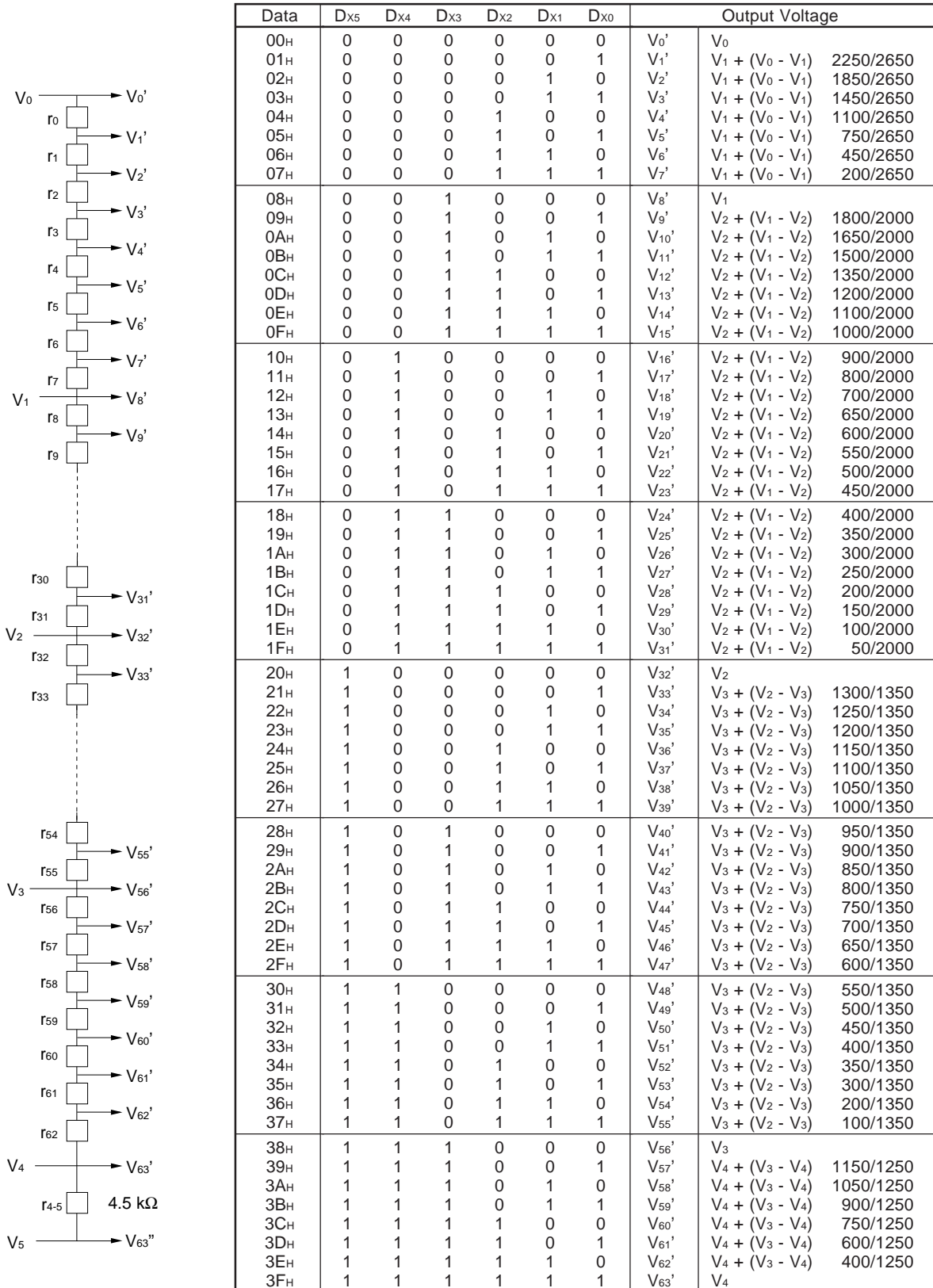
Because the current flowing through ladder resistors r_0 to r_{62} is small, its use for double-sided mounting impairs the IC's stable operation when the level of the γ -corrected power supply terminal is inverted thus causing display failures.

Figure 1. Relationship Between Input Data and Output Voltage



Resistor Strings

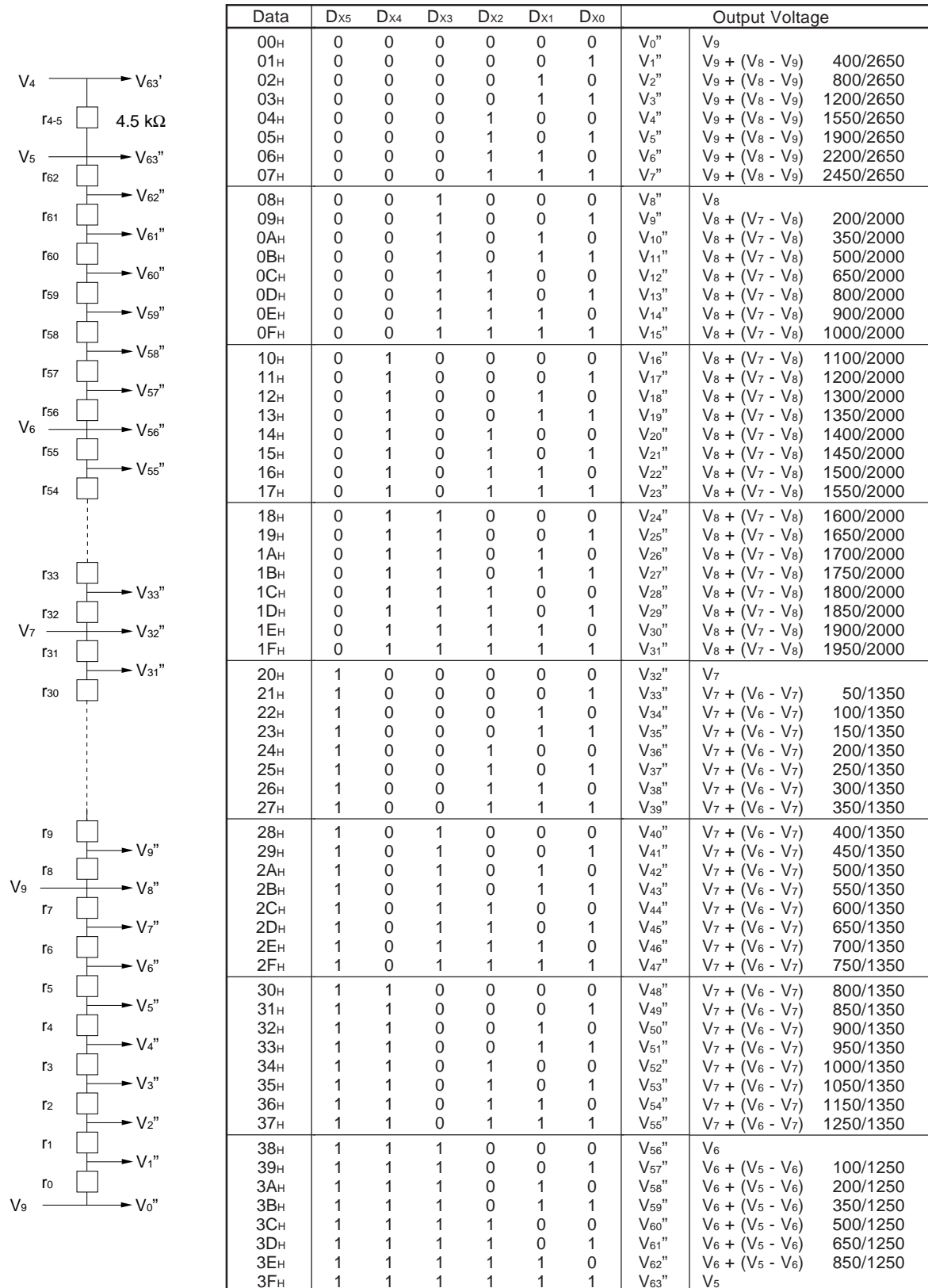
Figure 2-1. Relationship Between Input Data and Output Voltage: $V_{DD2} > V_0 > V_1 > V_2 > V_3 > V_4 > V_{SS2}$



Caution V4 and V5 are interconnected inside the IC by resistors r4-5 (4.5 kΩ).

Resistor Strings

Figure 2-1. Relationship Between Input Data and Output Voltage: $V_{DD2} > V_5 > V_6 > V_7 > V_8 > V_9 > V_{SS}$



Caution V4 and V5 are interconnected inside the IC by resistors r4-5 (4.5 kΩ).

Ladder Resistance Values (r0 to r62): Reference Value

Resistor Name	Resistance Value ()	Resistor Name	Resistance Value ()
r0	400	r32	50
r1	400	r33	50
r2	400	r34	50
r3	350	r35	50
r4	350	r36	50
r5	300	r37	50
r6	250	r38	50
r7	200	r39	50
r8	200	r40	50
r9	150	r41	50
r10	150	r42	50
r11	150	r43	50
r12	150	r44	50
r13	100	r45	50
r14	100	r46	50
r15	100	r47	50
r16	100	r48	50
r17	100	r49	50
r18	50	r50	50
r19	50	r51	50
r20	50	r52	50
r21	50	r53	100
r22	50	r54	100
r23	50	r55	100
r24	50	r56	100
r25	50	r57	100
r26	50	r58	150
r27	50	r59	150
r28	50	r60	150
r29	50	r61	200
r30	50	r62	400
r31	50	Total	7250

5. RELATIONSHIP BETWEEN INPUT DATA AND OUTPUT PIN

Data format : 6 bits × 2 RGBs (6 dots)

Input width : 36 bits (2-pixel data)

$R/\bar{L} = H$ (Right shift)

Output	S ₁	S ₂	S ₃	S ₄	S ₅	...	S ₃₁₁	S ₃₁₂
Data	D ₀₀ to D ₀₅	D ₁₀ to D ₁₅	D ₂₀ to D ₂₅	D ₃₀ to D ₃₅	D ₄₀ to D ₄₅	...	D ₄₀ to D ₄₅	D ₅₀ to D ₅₅

$R/\bar{L} = L$ (Left shift)

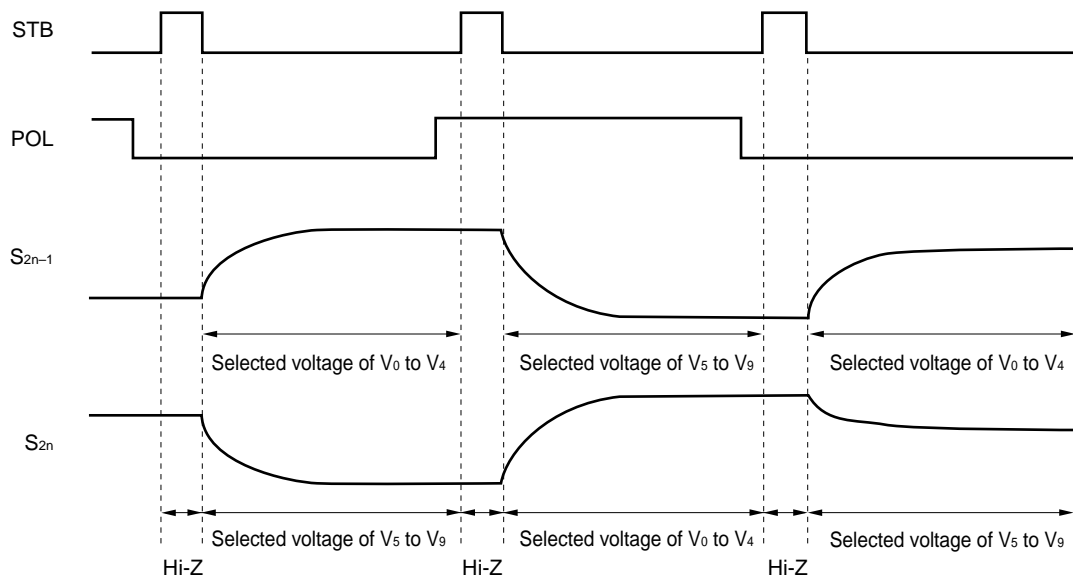
Output	S ₁	S ₂	S ₃	S ₄	S ₅	...	S ₃₁₁	S ₃₁₂
Data	D ₀₀ to D ₀₅	D ₁₀ to D ₁₅	D ₂₀ to D ₂₅	D ₃₀ to D ₃₅	D ₄₀ to D ₄₅	...	D ₄₀ to D ₄₅	D ₅₀ to D ₅₅

POL	S _{2n-1}	S _{2n}
L	V ₀ to V ₄	V ₅ to V ₉
H	V ₅ to V ₉	V ₀ to V ₄

S_{2n-1} (Odd output), S_{2n} (Even output) n = 1, 2,, 156

6. RELATIONSHIP BETWEEN STB, POL, AND OUTPUT WAVEFORM

The output voltage is written to the LCD panel synchronized with the STB rising edge.



Absolute Maximum Ratings (T_A = 25 °C, V_{SS1} = V_{SS2} = 0 V)

Parameter	Symbol	Rating	Unit
Logic Part Supply Voltage	V _{DD1}	-0.5 to +6.5	V
Driver Part Supply Voltage	V _{DD2}	-0.5 to +12.0	V
Logic Part Input Voltage	V _{I1}	-0.5 to V _{DD1} + 0.5	V
Driver Part Input Voltage	V _{I2}	-0.5 to V _{DD2} + 0.5	V
Logic Part Output Voltage	V _{O1}	-0.5 to V _{DD1} + 0.5	V
Driver Part Output Voltage	V _{O2}	-0.5 to V _{DD2} + 0.5	V
Total Power Dissipation	P _D	500	mW
Operating Temperature Range	T _A	-10 to +75	°C
Storage Temperature Range	T _{stg.}	-55 to +125	°C

Recommended Operating Range (T_A = -10 to +75 °C, V_{SS1} = V_{SS2} = 0 V)

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Logic Part Supply Voltage	V _{DD1}	3.0	3.3	3.6	V
Driver Part Supply Voltage	V _{DD2}	10.0	10.5	13.5	V
High-Level Input Voltage	V _{IH}	0.7 V _{DD1}		V _{DD1}	V
Low-Level Input Voltage	V _{IL}	0		0.3 V _{DD1}	V
γ-Corrected Voltage	V ₀ to V ₉	V _{SS2} + 0.05		V _{DD2} - 0.05	V
Driver Part Output Voltage	V _O	V _{SS2} + 0.1		V _{DD2} - 0.1	V
Maximum Clock Frequency	f _{max.}	45			MHz

Electrical specifications (T_A = -10 to +75 °C, V_{DD1} = 3.3 V ±0.3 V, V_{DD2} = 10.5 V ±0.5 V, V_{SS1} = V_{SS2} = 0 V)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input Leak Current	I _L				±1.0	μA
High-Level Output Voltage	V _{OH}	STHR (STHL), I _o = 0 mA	V _{DD1} - 0.1			V
Low-level Output Voltage	V _{OL}	STHR (STHL), I _o = 0 mA			0.1	V
γ-Corrected Supply Current		V ₀ - V ₉ = 10 V		0.6	1.0	mA
Driver Output Current	I _{VOH}	V _X = 9 V, V _{OUT} = 3 V ^{Note}			-0.3	mA
	I _{VOL}	V _X = 3 V, V _{OUT} = 9 V ^{Note}	0.3			mA

Note V_X refers to the output voltage of analog output pins S₁ to S₃₁₂.

V_{OUT} refers to the voltage applied to analog output pins S₁ to S₃₁₂.

Electrical Specifications ($T_A = -10$ to $+75$ °C, $V_{DD1} = 3.3$ V ± 0.3 V, $V_{DD2} = 10.5$ V ± 0.5 V, $V_{SS1} = V_{SS2} = 0$ V)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Output Voltage Deviation ^{Note 1}	ΔV_O	Input data: 00H to 3FH		± 5	± 20	mV
Average Output Voltage Variation ^{Note 2}	ΔV_{AV}	Input data: 00H to 3FH		± 10		mV
Output Voltage Range	V_O	Input data: 00H to 3FH	0.1		$V_{DD2} - 0.2$	V
Logic Part Dynamic Current Consumption	I_{DD1}	V_{DD} ; when with no load ^{Notes 3, 4}		0.39	10	mA
Driver Part Dynamic Current Consumption	I_{DD21}	$V_{DD2} = 10.5 \pm 0.5$ V when with no load ^{Notes 3, 4}		2.7	8.0	mA
	I_{DD22}	$V_{DD2} = 13.5 \pm 0.5$ V when with no load ^{Notes 3, 4}		3.5	10.0	mA

- Notes 1.** The output voltage deviation refers to the voltage difference between adjoining output pins when the display data is the same (within the chip).
- 2.** The average output voltage variation refers to the average output voltage difference between chips. The average output voltage refers to the average voltage between chips when the display data is the same.
- 3.** The STB cycle is defined to be 20 μ s at $f_{CLK} = 45$ MHz.
The TYP. values refer to an all black or all white input pattern. The MAX. value refers to the measured values in the dot checkerboard input pattern.
- 4.** Refers to the current consumption per driver when cascades are connected under the assumption of XGA single-sided mounting (10 units).

Switching Characteristics ($T_A = -10$ to $+75$ °C, $V_{DD1} = 3.3$ V ± 0.3 V, $V_{DD2} = 10.5$ V ± 0.5 V, $V_{SS1} = V_{SS2} = 0$ V)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Start Pulse Delay Time	t_{PLH1}	$C_L = 25$ pF		8.8	15	ns
Driver Output Delay Time 1	t_{PHL2}	$C_L = 50$ pF, $R = 50$ k Ω		5.3	11	μ s
Driver Output Delay Time 2	t_{PHL3}	$C_L = 50$ pF, $R = 50$ k Ω		11	17	μ s
Driver Output Delay Time 3	t_{PLH2}	$C_L = 50$ pF, $R = 50$ k Ω		5.7	11	μ s
Driver Output Delay Time 4	t_{PLH3}	$C_L = 50$ pF, $R = 50$ k Ω		11	17	μ s
Input Capacitance 1	C_1	STHR, STHL excluded $T_A = 25$ °C		5	15	pF
Input Capacitance 2	C_2	STHR, STHL $T_A = 25$ °C		5	15	pF

Timing Requirement

($T_A = -10$ to $+75$ °C, $V_{DD1} = 3.3$ V ± 0.3 V, $V_{SS1} = V_{SS2} = 0$ V, $t_r = t_f = 8.0$ ns)

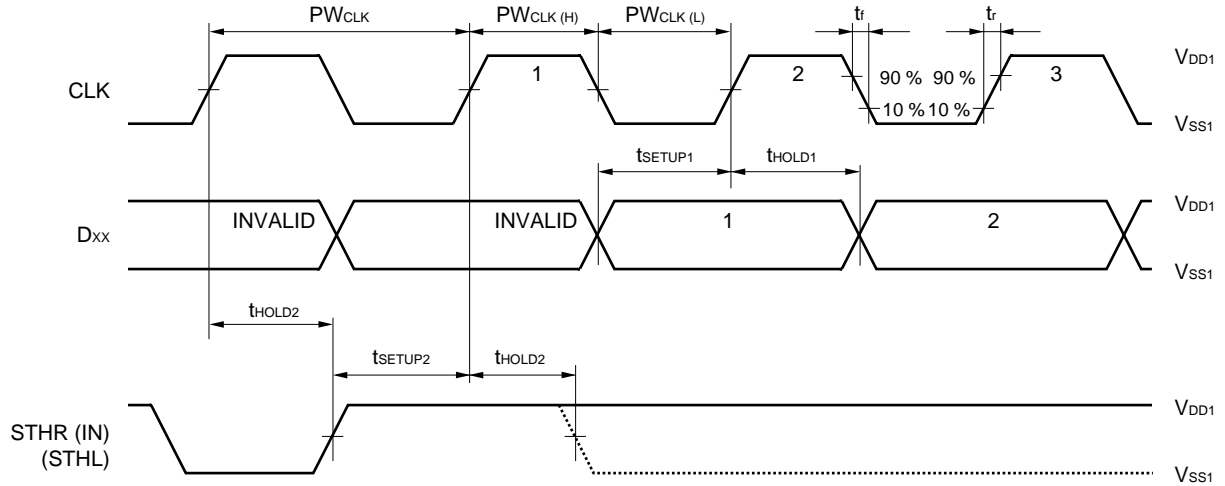
Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Clock Pulse Width	PW _{CLK}		22			ns
Clock Pulse Low Period	PW _{CLK(L)}		6			ns
Clock Pulse High Period	PW _{CLK(H)}		6			ns
Data Setup Time	t _{SETUP1}		6			ns
Data Hold Time	t _{HOLD1}		6			ns
Start Pulse Setup Time	t _{SETUP2}		6			ns
Start Pulse Hold Time	t _{HOLD2}		6			ns
Start Pulse Low Period	t _{SPL}		6			ns
STB Pulse Width	PW _{STB}		0.5			μs
Data Invalid Period	t _{INV}		1			CLK
Final Data Timing	t _{LDT}		2			CLK
CLK-STB Time	t _{CLK-STB}	CLK ↑ → STB ↓	6			ns
STB-CLK Time	t _{STB-CLK}	STB ↓ → CLK ↑	6			ns
Time Between STB and Start Pulse	t _{STB-STH}	STB ↓ → STHR ↑	60			ns
POL-STB Time	t _{POL-STB}	POL ↑ or ↓ → STB ↑	-5			ns
STB-POL Time	t _{STB-POL}	STB ↓ → POL ↑ or ↓	6			ns

Switching Characteristics Waveform (R/L = H)

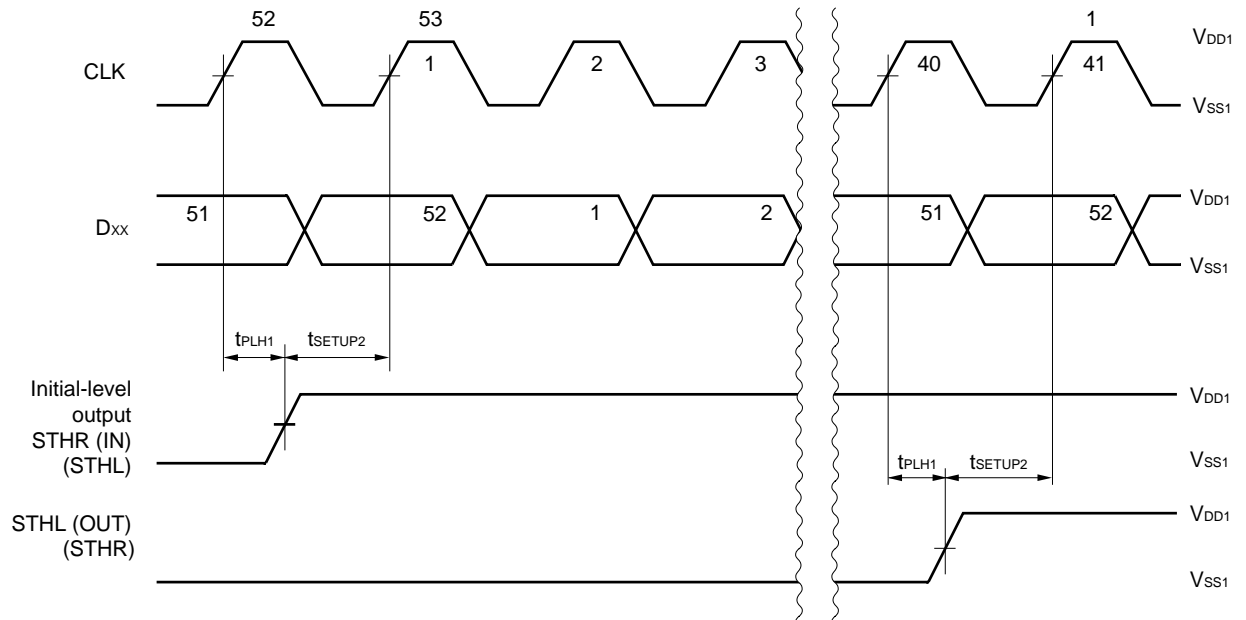
In () : R/L = L

Unless otherwise specified, the input level is defined to be 0.5 V_{DD1}.

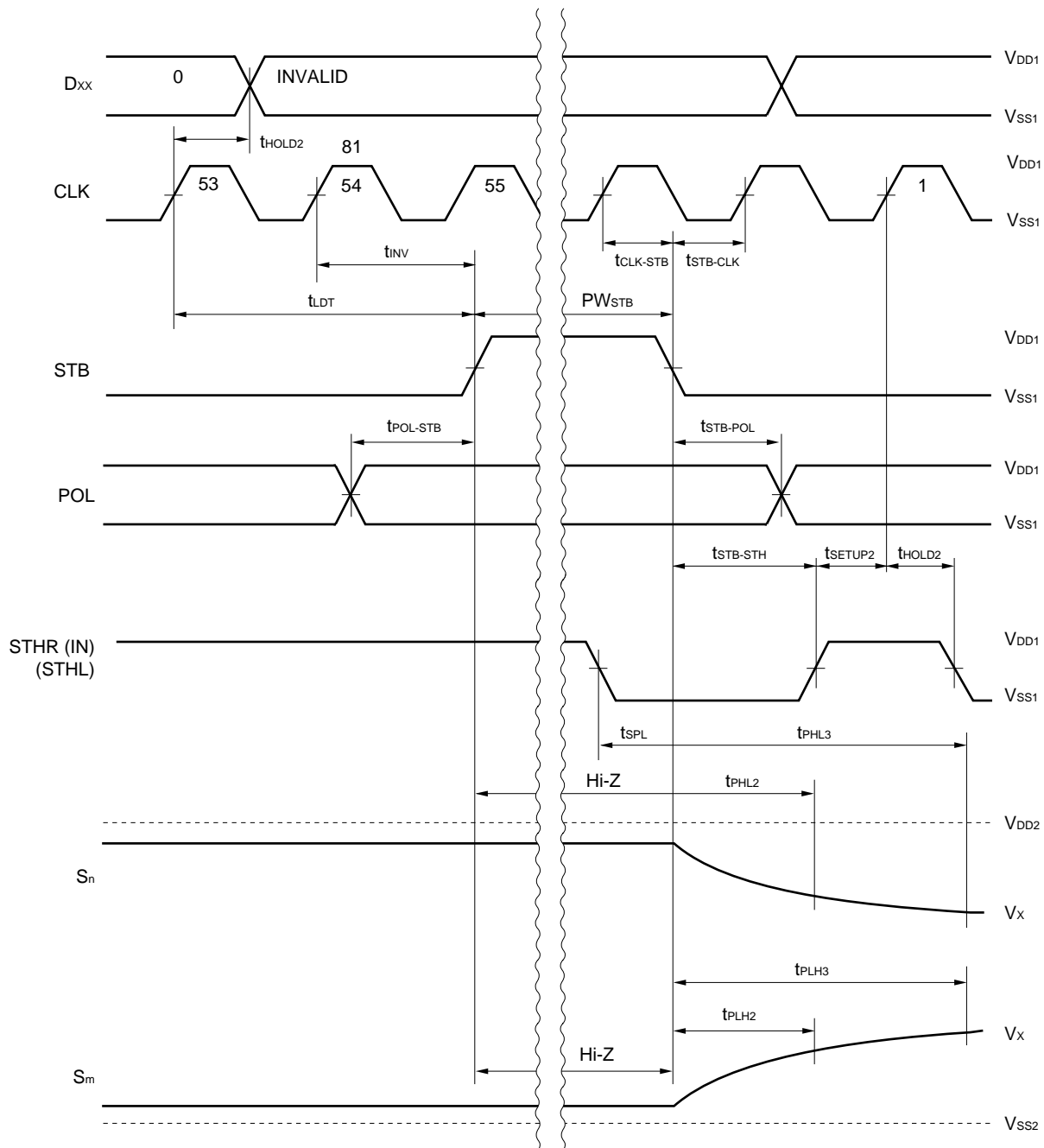
(1) Initial-Stage Driver's Input/Output Waveform



(2) Second- to Final-Stage Drivers's Input/Output Timing



(3) Driver Output Timing



V_x refers to the final output voltage. t_{PLH2} and t_{PHL2} refer to the time required to reach an output precision level of 10 % (0.1 V_x); and t_{PLH3} and t_{PHL3} refer to the time required to reach an output precision level of 6 bits.

RECOMMENDED MOUNTING CONDITIONS

When mounting this product, please make sure that the following recommended conditions are satisfied.

For packaging methods and conditions other than those recommended below, please contact NEC sales personnel.

Mounting Condition	Mounting Method	Condition
Thermocompression	Soldering	Heating tool 300 to 350 °C; heating for 2 to 3 seconds; pressure 100 g (per solder)
	ACF (Adhesive Conductive Film)	Temporary bonding 70 to 100 °C; pressure 3 to 8 kg/cm ² ; time 3 to 5 secs. Real bonding 165 to 180 °C; pressure 25 to 45 kg/cm ² ; time 30 to 40 secs. (when using the anisotropic conductive film SUMIZAC1003 of Sumitomo Bakelite, Ltd.)

Caution To find out the detailed conditions for packaging the ACF part, please contact the ACF manufacturing company. Be sure to avoid using two or more packaging methods at a time.

REFERENCE

NEC Semiconductor Device Reliability/Quality Control System (C10983E)

Quality Grades to NEC's Semiconductor Devices (C11531E)

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